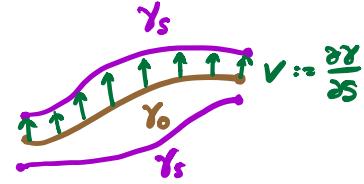


[Note: PS 4 due today, PS 5 posted and due on Apr 15.]

Recall: $(M, g) \rightsquigarrow f(p, q) := \inf_{\gamma} L(\gamma)$ metric space structure

$$\left[\frac{d}{ds} \Big|_{s=0} L(\gamma_s) = - \int_0^t \langle V, D_{\gamma} \gamma' \rangle dt + \langle V, \gamma' \rangle \Big|_{t=0}^{t=t} \right]$$



1st variation formula

Geodesics $\Leftrightarrow D_{\gamma} \gamma' = 0 \Leftrightarrow$ critical pts to L
(w.r.t. fixed end points)

Exponential map of (M, g) at $p \in M$:

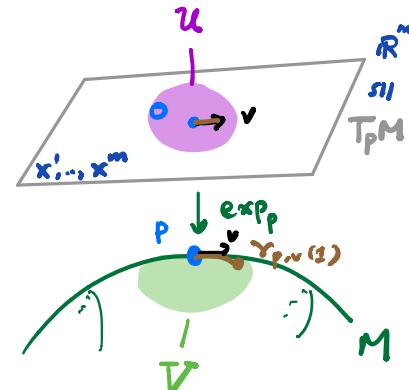
$$\exp_p : U^o \subseteq T_p M \xrightarrow[\text{local diff.}]{\cong} V \subseteq M$$

($\because \exp_p(0) = \text{Id}_{T_p M}$)

$$\exp_p(v) := \gamma_{p,v}(1)$$

Eucl. coord.
 x^1, \dots, x^m
on $T_p M \cong \mathbb{R}^m$

$\xrightarrow{\exp_p}$ geodesic normal
coord. near $p \in M$.



Properties of geodesic normal coord. $x^1, \dots, x^m \rightsquigarrow g_{ij}, T_{ij}^k$

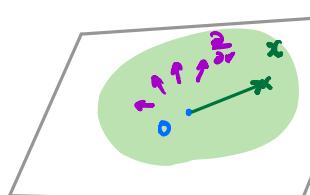
(1) $g_{ij}(0) = \delta_{ij}$ and $T_{ij}^k(0) = 0$. [In geod. normal coord.,

$$g_{ij}(x) = \delta_{ij} + O(|x|^2)$$

Curvature terms

(2) Gauss Lemma: $\sum_{j=1}^m g_{ij}(x) x^j = x^i$ — (*)

Geometric interpretation of (*):

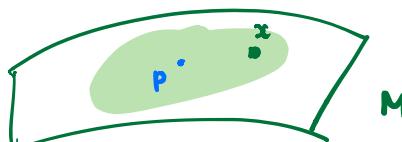


$$(T_p M, g_{ij}) \rightsquigarrow \|x\|_g := [g(x, x)]^{1/2}$$

$$(\mathbb{R}^m, \delta_{ij}) \rightsquigarrow r := |x| := [\delta(x, x)]^{1/2} = \left(\sum_{i=1}^m (x^i)^2 \right)^{1/2}.$$

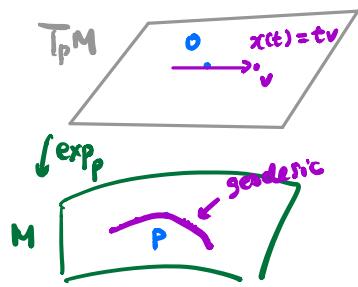
$$(*) \Leftrightarrow \|dr\|_g = 1$$

i.e. $\frac{\partial}{\partial r}$ is a unit vector field w.r.t. g



$$\left[\because dr = \sum_i \frac{x^i}{|x|} dx^i; \|dr\|_g^2 = \sum_{i,j} g^{ij}(x) \frac{x^i}{|x|} \frac{x^j}{|x|} = \frac{|x|^2}{|x|^2} = 1 \right]$$

"Proof": (1) $d\exp_p(0) = \text{Id} \Rightarrow g_{ij}(0) = \delta_{ij}$.



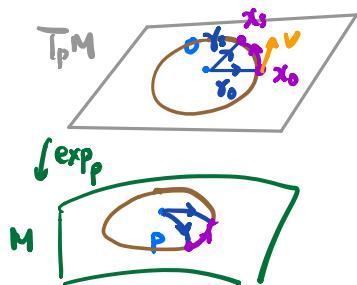
$t \mapsto \exp_p(tv)$ is a geodesic on $M \quad \forall v \in T_p M$

$$\text{geodesic eq}^2 \Rightarrow \frac{d^2 x^k}{dt^2} + T_{ij}^k(x(t)) \underbrace{\frac{dx^i}{dt}}_{v^i} \underbrace{\frac{dx^j}{dt}}_{v^j} = 0$$

$$\begin{aligned} \text{At } t=0 \Rightarrow T_{ij}^k(0) v^i v^j &= 0 \quad \forall v \in T_p M \\ \Rightarrow T_{ij}^k(0) &= 0 \text{ for all } i,j,k. \end{aligned}$$

(2)

Fix $x_0 \in T_p M$, consider $\gamma_s : [0,1] \rightarrow M$ given in g.n.c. by



$$\gamma_s(t) = t x_0$$

where $s \mapsto x_s$ is a smooth curve on the

$$\text{"sphere"} \{x \in T_p M : \|x\| = \|x_0\|\} \subseteq T_p M.$$

Note: • For every fixed s ,

(*) γ_s is a geodesic in M , with length $\|x_0\|$ and speed $= \|x_0\|$.

$$(\#*) \left\{ \begin{array}{l} \cdot \gamma_s(0) \equiv 0 \quad \forall s \\ \cdot \frac{d}{ds} \Big|_{s=0} \gamma_s(1) = \frac{d}{ds} \Big|_{s=0} x_0 = v \end{array} \right.$$

Notice: $v \perp x_0$ w.r.t. flat metric

$$\text{i.e. } \sum_{i=1}^m v^i x_0^i = 0$$

Idea: Apply 1st var. formula for L to $s \mapsto \gamma_s$.

$$0 \stackrel{(\#)}{=} \frac{d}{ds} \Big|_{s=0} L(\gamma_s) = - \int_0^1 \langle V, D_{x_s} x_s' \rangle_g dt + \underbrace{\langle V, x_0' \rangle_g}_{\equiv 0 \text{ by } (\#)} \Big|_{t=0}^{t=1} \stackrel{\text{by } (\#*)}{=} \langle V, x_0' \rangle_g(1)$$

$$\Rightarrow \sum_{i,j} g_{ij}(x_0) x_0^i v^j = 0 \quad \forall v \text{ s.t. } v \perp x_0$$

$$\Rightarrow \sum_i g_{ij}(x_0) x_0^i \frac{\partial}{\partial x^j} \parallel x_0^i \frac{\partial}{\partial x^j} \quad \text{w.r.t. flat metric } \delta$$

$$\text{Also, } \sum_{i,j} g_{ij}(x_0) x_0^i x_0^j \stackrel{(*)}{=} \|x_0'(1)\|_g^2 = \|x_0\|^2 = \sum_i (x_0^i)^2 \Rightarrow \sum_i g_{ij}(x_0) x_0^i = x_0^j$$

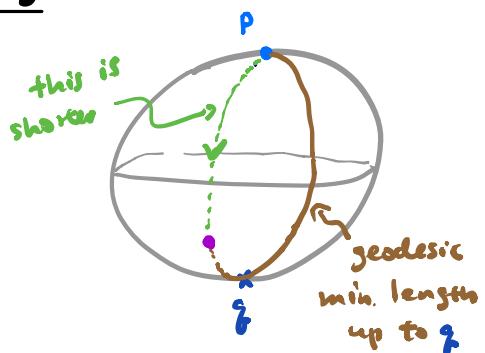
Minimizing Properties of geodesics

Recall: "geodesics" \Leftrightarrow "straight lines" in (M, g)

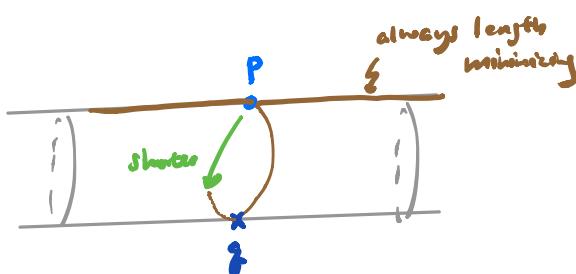
Q: How much does geodesics min. distance between 2 points?

FACT: "Short" geodesics minimizes length between its end points.
But not nec. true for "long" geodesics.

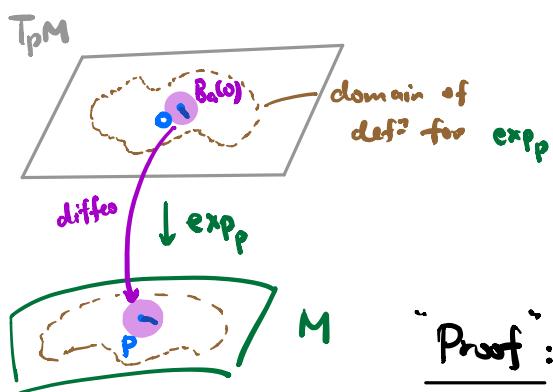
E.g.) $M = S^2 \subseteq \mathbb{R}^3$.



$M = S^1 \times \mathbb{R} \subseteq \mathbb{R}^3$



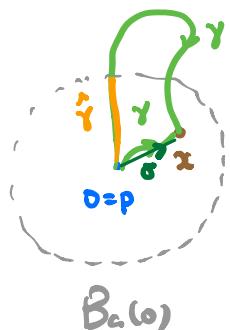
Prop: If \exp_p is a diffeo. onto its image on $B_a(0) = \{x \in T_p M \mid \|x\| < a\}$,



THEN: $\forall x \in B_a(0)$, the ray $x(t) = tx$, $0 \leq t \leq 1$ is the unique length-minimizing geodesic from p to $x(1)$. (i.e. $L(x(t)) = \rho(p, x(1))$)

"Proof": By Gauss Lemma, $\|\mathrm{d}r\|_g \equiv 1$.

Case 1: γ stays inside $B_a(0)$



$$L(\gamma) = \int_{\gamma} ds \geq \int_{\gamma} dr = \|x\| = L(\sigma) < a$$

\uparrow arc length γ

Case 2: γ leaves the ball $B_a(0)$ somewhere

$$L(\gamma) \geq L(\hat{\gamma}) \geq a$$

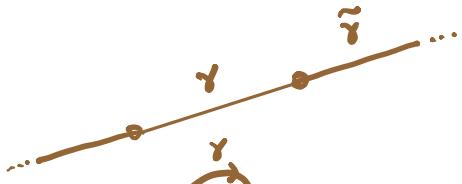
Complete Riem. manifold

Recall: $(M, g) \rightsquigarrow (M, f)$ metric space

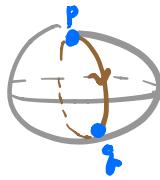
Metric space completeness: Every Cauchy seq. is convergent.

Q: How does this relate to g ?

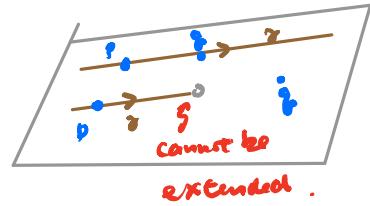
Defⁿ: (M, g) geodesically complete if any geodesic in M can be extended indefinitely, i.e. $\exp_p: T_p M \rightarrow M$ is defined on the whole $T_p M$. $\forall p \in M$



E.g.) cpt Riem. mfd
are always geod. complete



Non-Eg.: $\mathbb{R}^2 \setminus \{0\} = M$
is not complete.



Hopf-Rinow Thm: Geodesic completeness \Leftrightarrow metric completeness.

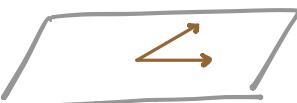
"Proof": HW exercise! [Key fact: complete $\Rightarrow \exists$ min. geod. γ joining any two points]

Q: How does the "curvatures" of (M, g) affect the behavior of geodesics?

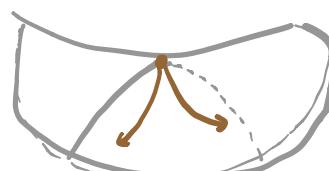
Recall: $\Sigma \subseteq \mathbb{R}^3$ surface



$$K > 0$$



$$K = 0$$



$$K < 0$$

Idea: In higher dimensions, the sectional curvatures affects the geodesics through 2nd variation of Length or "energy"

Defⁿ: Given a curve $\gamma: [a, b] \rightarrow (M, g)$, the energy of γ is:

$$E(\gamma) := \int_a^b \|\gamma'(t)\|_g^2 dt$$

Remarks: (1) $L(\gamma) := \int_a^b \|\gamma'(t)\|_g dt$ is indep of parametrization

BuT: $E(\gamma)$ depends on the parametrization as well.

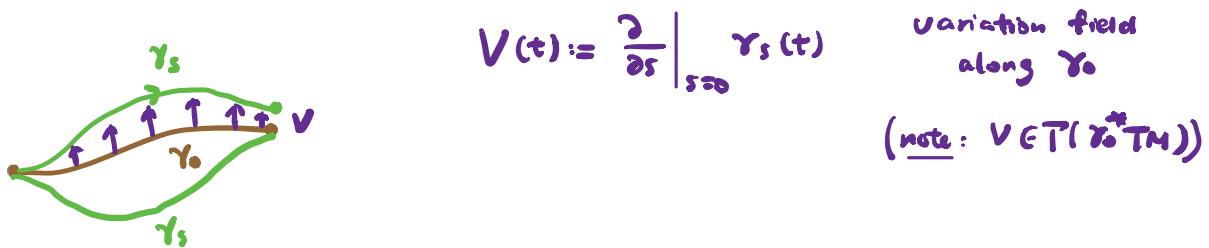
(2) $E(\gamma)$ does not involve $\sqrt{\cdot}$, so it's easier to compute its derivative.

Note: (a) Hölder $\Rightarrow L(\gamma)^2 \leq (b-a) \cdot E(\gamma)$.

$$(b) f(p, q) := \inf_{\gamma} L(\gamma) = \inf_{\gamma} E(\gamma)^{1/2} \quad (\text{Take } b-a=1).$$

1st & 2nd variations of energy

Setup: Let $\gamma_s(t): [0, 1] \rightarrow M$, $s \in (-\varepsilon, \varepsilon)$, be a 1-parameter family of curves in M .



$$V(t) := \left. \frac{\partial}{\partial s} \right|_{s=0} \gamma_s(t)$$

variation field
along γ_0

(note: $V \in T(\gamma_0 TM)$)

$$\frac{1}{2} \left. \frac{d}{ds} \right|_{s=0} E(\gamma_s) = - \int_0^1 \langle V, D_{\frac{\partial}{\partial t}} \gamma'_s \rangle_g dt + \langle \gamma'_0, V \rangle \Big|_{t=0}^{t=1}$$

1st var. formula for energy Proof: Ex!

Remark: (i) We do NOT need to assume γ_0 is p.b.a.l.

wl.
fixed
end pts

{ (ii) γ is a critical pt. of $E \Leftrightarrow (D_{\gamma'} \gamma')' \equiv 0$, ie. γ geodesic
(iii) γ is a critical pt. of $L \Leftrightarrow (D_{\gamma'} \gamma')' \equiv 0$

Suppose: $\gamma = \gamma_0$ is a closed geodesic.

Then, we have the 2nd variation formula for energy:

$$\frac{1}{2} \frac{d^2}{ds^2} \Big|_{s=0} E(\gamma_s) = \int_0^1 \left(\underbrace{\| D_{\frac{\partial}{\partial t}} V \|_g^2}_{\text{non-negative}} - \underbrace{R(\gamma', V, \gamma', V)}_{\text{sectional curvature term}} \right) dt$$

Proof: Write $F(t, s) = \gamma_s(t)$.

$$\begin{aligned} \text{1st var. formula : } \forall s \in (-\epsilon, \epsilon) \quad & \frac{1}{2} \frac{d}{ds} E(\gamma_s) = - \int_0^1 \left\langle D_{\frac{\partial}{\partial t}}, \frac{\partial F}{\partial s} \right\rangle dt \\ & \stackrel{\text{I.b.p.}}{=} \int_0^1 \left\langle \frac{\partial F}{\partial t}, D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle dt \end{aligned}$$

As

Differentiate in s again, and take $s=0$:

$$\begin{aligned} \frac{1}{2} \frac{d^2}{ds^2} \Big|_{s=0} E(\gamma_s) &= \int_0^1 \left[\left\langle D_{\frac{\partial}{\partial s}} \frac{\partial F}{\partial t}, D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle + \left\langle \frac{\partial F}{\partial t}, D_{\frac{\partial}{\partial s}} D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle \right] dt \\ \left(\begin{array}{l} \text{torsion-free} \\ \downarrow \\ D_{\frac{\partial}{\partial s}} \frac{\partial F}{\partial t} = D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \end{array} \right) &= \int_0^1 \left[\left\langle D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s}, D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle + \left\langle \frac{\partial F}{\partial t}, D_{\frac{\partial}{\partial s}} D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle \right] dt \\ \left(\begin{array}{l} \text{using def:} \\ + R \end{array} \right) \rightarrow &= \int_0^1 \left[\| D_{\frac{\partial}{\partial t}} V \|_g^2 + \left\langle \frac{\partial F}{\partial t}, D_{\frac{\partial}{\partial s}} D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s} \right\rangle \right. \\ &\quad \left. - R \left(\frac{\partial F}{\partial s}, \frac{\partial F}{\partial t}, \frac{\partial F}{\partial s}, \frac{\partial F}{\partial t} \right) \right] dt \\ &= \int_0^1 \| D_{\frac{\partial}{\partial t}} V \|_g^2 - R(V, \gamma', V, \gamma') dt \\ &\quad - \underbrace{\int_0^1 \left\langle D_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s}, D_{\frac{\partial}{\partial s}} \frac{\partial F}{\partial s} \right\rangle dt}_{s=0} \\ &= 0 \quad \because \text{So geodesic} \end{aligned}$$

□

$$\text{Def: } I(V, V) := \int_0^1 \left(\| D_{\frac{\partial}{\partial t}} V \|_g^2 - R(\gamma', V, \gamma', V) \right) dt \quad \forall V \in T(Y^*TM)$$

is called the index form of a geodesic γ .

Note: polarize $\sim I(V, W)$ symmetric bilinear.

Prop: $V \in \ker I$ (ie $I(V, W) = 0 \quad \forall W \in T(\gamma^* TM)$)

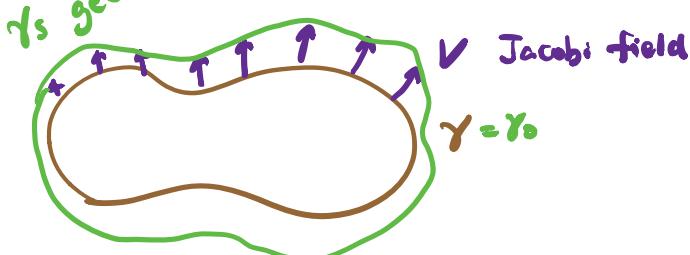
\Leftrightarrow

$$D_{\frac{\partial}{\partial t}} D_{\frac{\partial}{\partial t}} V + R(\gamma', V) \gamma' = 0$$

Jacobi field equation
(2nd order linear).

Thm: Jacobi fields V arise exactly from 1-parameter family of geodesics $\{\gamma_s\}_{s \in (-\varepsilon, \varepsilon)}$ st $\gamma_0 = \gamma$.

γ_s geodesic $\forall s$



Proof: Exercise HW.

Idea: geodesics $\Leftrightarrow D_{\gamma'} \gamma' = 0$

(2nd order non-linear)

Jacobi field \Leftrightarrow "linearization"
of $D_{\gamma'} \gamma' = 0$

$$D_{\gamma_s} \gamma_s' = 0 \quad \forall s \in (-\varepsilon, \varepsilon).$$

(2nd order linear)

$$\Rightarrow \left. \frac{d}{ds} \right|_{s=0} (D_{\gamma_s} \gamma_s' = 0) \rightsquigarrow \text{Jacobi field } e.g. \gamma''$$